

# Multi-core Architecture and Programming

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## Threads

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- Content

- ◆ Windows threads library
- ◆ Using the Windows thread API
- ◆ Synchronization

# Windows threads library

- **Win32 API** is the interface between the kernel and applications. It is a package of system functions that can be called by application
- **MFC** is Microsoft Foundation Classes, it pack the Win32 API as classes.
- **.NET Framework** include Common Language Runtime (CLR) and Framework Class Library (FCL). **System.Threading** name space in .NET Foundation Classes offer the class and interfaces to support the thread.

# Programming with Windows Threads

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- **Content**
  - ◆ **Windows threads library**
  - ◆ **Using the Windows thread API**
  - ◆ **Synchronization**

# Using the Windows thread API

- Win32\* HANDLE type
  - ◆ Each Windows object is referenced by HANDLE type variables
    - ☞ Pointer to kernel objects
    - ☞ Thread, process, file, event, mutex, semaphore, etc.
  - ◆ Object creation functions return HANDLE
  - ◆ Object controlled through its handle
    - ☞ Don't manipulate objects directly

# Using the Windows thread API

## ■ Win32\* Thread Creation

```
static HANDLE CreateThread(  
    LPSECURITY_ATTRIBUTES lpsa,  
    DWORD dwStackSize,  
    LPTHREAD_START_ROUTINE pfnThreadProc,  
    void* pvParam,  
    DWORD dwCreationFlags,  
    DWORD* pdwThreadId );
```

***lpsa***: The security attributes for the new thread.

***dwStackSize***: The stack size for the new thread.

***pfnThreadProc***: The thread procedure of the new thread.

***pvParam***: The parameter to be passed to the thread procedure.

***dwCreationFlags***: The creation flags (0 or CREATE\_SUSPENDED).

***pdwThreadId***: [out] Address of the DWORD variable that, on success, receives the thread ID of the newly created thread.

# Using the Windows thread API

- **LPTHREAD\_START\_ROUTINE**
  - ◆ **CreateThread() expects pointer to global function**
    - ☞ Returns **DWORD**
    - ☞ Calling convention **WINAPI**
    - ☞ Single **LPVOID (void \*)** parameter

```
DWORD WINAPI MyThreadStart(LPVOID p);
```

- ◆ **Thread begins execution of function**

# Using the Windows thread API

- Using Explicit Threads
  - ◆ Identify portions of code to thread
  - ◆ Encapsulate code into function
    - ☞ If code is already a function, a driver function may need to be written to coordinate work of multiple threads
  - ◆ Add `CreateThread` call to assign thread(s) to execute function



# Using the Windows thread API

## ■ Manage the threads

### ◆ Set the priority

☞ Thread PRI = process PRI + thread relative PRI

☞ *Bool SetThreadPriority (HANDLE hPriority, int nPriority)*

### ◆ Suspend and resume the thread

☞ If suspend count in thread = 0, thread executed. If it > 0, scheduler will not schedule the thread.

☞ *DWORD SuspendThread (HANDLE hThread);*

☞ *DWORD ResumeThread (HANDLE hThread);*



# Using the Windows thread API

- Manage the threads
  - ◆ Waiting for thread
    - ☞ *WaitForSingleObject*
    - ☞ *WaitForMultipleObjects*
  - ◆ Exit thread
    - ☞ *ExitThread(DWORD dwExitCode)*
    - ☞ *TerminateThread(HANDLE hThread, DWORD dwExitCode)*
  - ◆ Destroying Threads
    - ☞ *Frees OS resources*
      - Clean-up if done with thread before program completes

**BOOL CloseHandle(HANDLE hObject);**



# Using the Windows thread API

## ■ Example: Thread Create

```
#include <stdio.h>
#include <windows.h>

DWORD WINAPI helloFunc(LPVOID arg) {
    printf("Hello Thread");
    return 0;
}

Main() {
    HANDLE hThread =
        CreateThread(NULL, 0, helloFunc, NULL, 0, NULL);
}
```

## What Happens?

# Using the Windows thread API

- Example Explained
  - ◆ Main thread is process
  - ◆ When process goes, all thread goes
  - ◆ Need some method of waiting for a thread to finish

# Using the Windows thread API

## ■ Waiting for Windows\* Thread

```
#include <stdio.h>
#include <windows.h>
BOOL threadDone = FALSE;

DWORD WINAPI helloFunc(LPVOID arg) {
    printf("Hello Thread");
    threadDone = TRUE;
    return 0;
}

Main() {
    HANDLE hThread =
        CreateThread(NULL, 0, helloFunc, NULL, 0, NULL);
    While (!threadDone); // wasted cycles
}
```

**Not a good ideal!**



# Using the Windows thread API

- Waiting for a thread
  - ◆ Wait for one object (thread)

```
DWORD WaitForSingleObject(  
    HANDLE hHandle,  
    DWORD dwMilliseconds );
```

- ◆ Call thread waits (blocks) until
  - ☞ Time expires
    - Return code use to indicate this
  - ☞ Thread exits (handle is signaled)
    - Use INFINITE to wait until thread termination

- ◆ Dose not use CPU cycles

# Using the Windows thread API

- Waiting for Many threads
  - ◆ Wait for up to 64 objects (threads)

```
DWORD WaitForMultipleObjects(  
    DWORD nCount,  
    const HANDLE* lpHandles, // array  
    BOOL bWaitAll, // wait for one or all  
    DWORD dwMilliseconds );
```

- ☞ Wait for all: `bWaitAll = TRUE`
- ☞ Wait for any: `bWaitAll = FALSE`
- ☞ Return value is first array index found

# Using the Windows thread API

- Notes on WaitFor\* Functions
  - ◆ Handle as parameter
  - ◆ Used for different types of objects
  - ◆ Kernel objects have two states
    - ☞ Signaled
    - ☞ Non-signaled
  - ◆ Behavior is defined by object referred to by handle
    - ☞ Thread: signaled means terminated




# Using the Windows thread API

## ■ Example: Multiple Thread

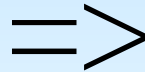
```
#include <stdio.h>
#include <windows.h>
const int numThread = 4;
DWORD WINAPI helloFunc(LPVOID arg) {
    printf("Hello Thread");
    return 0;
}
Main() {
    HANDLE hThread[numThread];
    for (int i = 0; i < numThread; i++)
        hThread[i] =
            CreateThread(NULL, 0, helloFunc, NULL, 0, NULL);
    WaitForMultipleObjects(numThreads, hThread, TRUE, INFINITE);
}
```

# Using the Windows thread API

- How to print the thread number?



```
C:\WINDOWS\system32\cmd.exe
Hello Thread
Hello Thread
Hello Thread
Hello Thread
请按任意键继续...
```



```
Hello from Thread #0
Hello from Thread #1
Hello from Thread #2
Hello from Thread #3
```

# Using the Windows thread API

- Is that right? Why or why not?

```
#include <stdio.h>
#include <windows.h>
const int numThread = 4;
DWORD WINAPI helloFunc(LPVOID pArg) {
    int* p = (int *)pArg;
    int mynum = *p;
    printf("Hello Thread %d\n",mynum);
    return 0;
}
main() {
    HANDLE hThread[numThreads];
    for (int i = 0; i < numThreads; i++)
        hThread[i] =
            CreateThread(NULL, 0, helloFunc, &i, 0, NULL );
}
```



# Using the Windows thread API

## ■ Hello threads Timeline

<i>Time</i>	<i>main</i>	<i>Thread 0</i>	<i>Thread 1</i>
T <sub>0</sub>	<b>i = 0</b>	---	----
T <sub>1</sub>	create(&i)	---	---
T <sub>2</sub>	<b>i++ (i == 1)</b>	launch	---
T <sub>3</sub>	create(&i)	p = pArg	---
T <sub>4</sub>	<b>i++ (i == 2)</b>	myNum = *p <b>myNum = 2</b>	launch
T <sub>5</sub>	wait	print(2)	p = pArg
T <sub>6</sub>	wait	exit	myNum = *p <b>myNum = 2</b>

# Programming with Windows 多核技术与编程

## Threads

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- **Content**
  - ◆ Windows threads library
  - ◆ Using the Windows thread API
  - ◆ **Synchronization**

# Synchronization

- Race Conditions
  - ◆ Concurrent access of same variable by multiple threads
    - ☞ Read/Write conflict
    - ☞ Write/Write conflict
  - ◆ Most common error in concurrent programs
  - ◆ May not be apparent at all times

# Synchronization

- How to Avoid Data Races
  - ◆ Scope variables to be local to threads
    - ☞ Variables declared within threaded functions
    - ☞ Allocate on thread's stack
    - ☞ TLS (Thread Local Storage)
  - ◆ Control shared access with critical regions
    - ☞ Mutual exclusion and synchronization
    - ☞ Lock, semaphore, event, critical section, mutex...

# Synchronization

## ■ Solution - "local" Storage

```
DWORD WINAPI helloFunc(LPVOID pArg)
{
    int mynum = *((int *)pArg);
    printf("Hello Thread %d\n",mynum);
    return 0;
}

// from main
int tNum[numThreads];
for (int i = 0; i < numThreads; i++){
    tNum[i] = i;
    hThread[i] =
        CreateThread(NULL, 0, helloFunc, &tNum[i], 0, NULL );
}
WaitForMultipleObjects(numThreads, hThread, TRUE, INFINITE);
```



# Synchronization

- Win32\* Mutexes
  - ◆ Kernel object reference by handle
  - ◆ “Signaled” when available
  - ◆ Operations:
    - `CreateMutex(...)` // create new
    - `WaitForSingleObject` // wait & lock
    - `ReleaseMutex(...)` // unlock
  - ◆ Available between processes

# Synchronization

- Win32\* Critical Section
  - ◆ Lightweight, intra-process only mutex
  - ◆ Most useful and most used
  - ◆ New type
    - ↳ `CRITICAL_SECTION cs;`
  - ◆ Create and destroy operations
    - ↳ `InitializeCriticalSection(&cs)`
    - ↳ `DeleteCriticalSection(&cs);`

# Synchronization

## ■ Win32\* Critical Section

```
CRITICAL_SECTION cs ;
```

Attempt to enter protected code

```
EnterCriticalSection(&cs)
```

- ↳ Blocks if another thread is in critical section
- ↳ Returns when no thread is in critical section

Upon exit of critical section

```
LeaveCriticalSection(&cs)
```

- ↳ Must be from obtaining thread

# Synchronization

## ■ Example: Computing Pi

```
static long num_steps=1000000;
double step, pi;

void main()
{ int i;
  double x, sum = 0.0;

  step = 1.0/(double) num_steps;
  for (i=0; i< num_steps; i++){
    x = (i+0.5)*step;
    sum = sum + 4.0/(1.0 + x*x);
  }
  pi = step * sum;
  printf("Pi = %12.9f\n",pi);
}
```

Parallelize the numerical integration code using Win32 Threads

How can the loop iterations be divided among the threads?

What variables can be local?

What variables need to be visible to all threads?

# Synchronization

- Win32\* Semaphores
  - ◆ Synchronization object that keeps a count
    - ☞ Represents the number of available resources
    - ☞ Formalized by Edsger Dijkstra (1968)
  - ◆ Two operations on semaphores
    - ☞ Wait [P(s)]: Thread waits until  $s > 0$ , then  $s = s - 1$
    - ☞ Post [V(s)]:  $s = s + 1$
  - ◆ Semaphore is in signaled state if count  $> 0$

# Synchronization

## ■ Win32\* Semaphore Creation

```
HANDLE CreateSemaphore(  
    LPSECURITY_ATTRIBUTES lpSemaphoreAttributes,  
    LONG lInitialCount, // Initial count for the semaphore object  
    LONG lMaximumCount, // Maximum value for count  
    LPCTSTR lpName ); // text name for object
```

- ◆ Value of **lMaximumCount** must be greater than zero.
- ◆ Value of **lInitialCount** must be
  - Greater than or equal to zero
  - Less than or equal to **lMaximumCount**
  - Cannot go outside of range



# Synchronization

- Wait and Post Operations
  - ◆ Use WaitForSingleObject to wait on semaphore
    - ☞ If count is == 0, thread waits
    - ☞ Decrement count by 1 when count > 0
  - ◆ Increment semaphore (Post operation)

```
BOOL ReleaseSemaphore(  
    HANDLE hSemaphore,  
    LONG cReleaseCount,  
    LPLONG lpPreviousCount
```

- ☞ Increase semaphore count by cReleaseCount
- ☞ Returns the previous count through lpPreviousCount

# Synchronization

## ■ Semaphore Uses

- ◆ Control access to data structures of limited size
  - ☞ Queues, stacks, dequeues
  - ☞ Use count to enumerate available elements
- ◆ Control access to finite number of resource
  - ☞ File descriptors, tape drives...
- ◆ Throttle number of active threads within a region
- ◆ Binary semaphore  $[0, 1]$  can act as mutex



# Synchronization

- Semaphore Cautions
  - ◆ No ownership of semaphore
  - ◆ Any thread can release a semaphore, not just the last thread that waits
    - ☞ Use good programming practice to avoid this
  - ◆ No concept of abandoned semaphore
    - ☞ If thread terminates before post, semaphore increment may be lost
    - ☞ Deadlock

# Synchronization

- Example: Semaphore as Mutex
  - ◆ Main thread opens input file, waits for thread termination
  - ◆ Thread will
    - ↳ Read line from input file
    - ↳ Count all five\_letter words in line

# Synchronization

## ■ Example: Main

```
HANDLE hSem1, hSem2;  
FILE *fd;  
int fiveLetterCount = 0;
```

```
main()  
{ HANDLE hThread[NUMTHREAD];  
  hSem1 = CreateSemaphore(NULL,1,1,NULL); // Binary semaphore  
  hSem2 = CreateSemaphore(NULL,1,1,NULL); // Binary semaphore  
  fd = fopen("InFile", "r"); // open file for read  
  for (int i = 0; i < NUMTHREAD; i++)  
    hThread[i] = CreateThread(NULL, 0,CountFives,NULL,0,NULL);  
  WaitForMultipleObjects(NUMTHREAD, hThread, TRUE, INFINITE);  
  fclose(fd);  
  printf("Numbers of five letter words is %d\n", fiveLetterCount);  
}
```

# Synchronization

## ■ Example: Semaphores

```
DWORD WINAPI CountFives(LPVOID arg) {
    BOOL bDone = FALSE;
    char inLine[132]; int ICount = 0;
    while (!bDone)
    {
        WaitForSingleObject(hSem1, INFINITE); // access to input
        bDone = (GetNextLine(fd, inLine) == EOF);
        ReleaseSemaphore(hSem1, 1, NULL);
        if (!bDone)
            if (ICount = GetFiveLetterWordCount(inLine)) {
                WaitForSingleObject(hSem2, INFINITE); // update global
                fiveLetterCount += ICount;
                ReleaseSemaphore(hSem2, 1, NULL);
            }
    }
}
```

# Synchronization

- Win32\* Events
  - ◆ Used to signal other threads that some event has occurred
    - ☞ Data is available, message is ready
  - ◆ Threads wait for signal with `WaitFor*` function
  - ◆ Two kinds of events
    - ☞ Auto-reset
    - ☞ Manual-reset

# Synchronization

## ■ Types of Events

### Auto-reset

- Event stays signaled until any one thread waits and is released
  - ◆ If no threads waiting, state stays signaled
  - ◆ Once thread is released, state reset to non-signaled

### Manual-reset

- Event remains signaled until reset by API call
  - ◆ Multiple threads can wait and be released
  - ◆ Threads not originally waiting may start wait and be released

**Caution: Be careful when using `WaitForMultipleObjects` to wait for ALL events**

# Synchronization

```
HANDLE CreateEvent(  
    LPSECURITY_ATTRIBUTES lpEventAttributes,  
    BOOL, bManualReset  
    BOOL bInitialState,  
    LPCTSTR lpName );
```

- Set *bManualReset* to TRUE for manual-reset event; FALSE for Auto reset event.
- Set *bInitialState* to TRUE for event to begin in signaled state; FALSE to begin unsignaled.

# Synchronization

- Event set and Reset
  - ◆ Set an event to signaled state

```
BOOL SetEvent( HANDLE hEvent );
```

- ◆ Reset manual-reset event

```
BOOL ResetEvent( HANDLE hEvent );
```

- ◆ Pulse event

```
BOOL PulseEvent( HANDLE hEvent );
```